MAPPING CONDITIONAL DISTRIBUTIONS FOR DOMAIN ADAPTATION UNDER GENERALIZED TARGET SHIFT ICLR 2022

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Introduction



Unsupervised Domain Adaptation (UDA)

Train a good classifier $h : \mathcal{X} \to \mathcal{Y}$ for an **unlabelled** target domain \mathcal{T} given a labelled source domain S.



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Generalized Target Shift

We consider the most challenging UDA setting, Generalized target shift (GeTarS) $_{\text{Zhang et al. 2013}}$ where: $p_S(X|Y) \neq p_T(X|Y), p_S(Y) \neq p_T(Y)$

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UDA under generalized target shift

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 $h: \mathcal{X} \xrightarrow{g} \mathcal{Z} \xrightarrow{f_{S}} \mathcal{Y}$ where g: encoder, $f_{S}:$ classifier,

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- Learn f_S to classify encoded S samples.
- Learn g to match encoded S and T samples.



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- Learn f_S to classify encoded S samples.
- Learn g to match encoded S and T samples.
- Under GeTarS, reweight S samples by estimated class-ratios.

Combes et al. 2020; Gong et al. 2016; Rakotomamonjy et al. 2021; Shui et al. 2021



Limitations of invariant representation learning

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Aligns pretrained representations with a NN mapping.

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- Aligns pretrained representations with a NN mapping.
- This mapping is regularized with Optimal Transport (OT):

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 - useful inductive biases for stability and performance.
 - under mild assumptions, provides two theoretical guarantees:

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 - explicit control of the target risk.

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 - explicit control of the target risk.
 - unicity of the solution.

OSTAR framework

Objectives

• Encode input S and T samples with g



Objectives

With fixed representations jointly

1 Map encoded S samples onto T with ϕ under OT constraints.



Objectives

- With fixed representations jointly
 - **2** Reweight mapped S samples with class-ratio estimates $\boldsymbol{p}_N^Y/\boldsymbol{p}_S^Y$.



Objectives

With fixed representations jointly

3 Train classifier f_N on reweighted and mapped S samples



Objectives

• Use f_N for inference on encoded T samples.





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- \blacksquare We define mild assumptions on g, for which
 - OSTAR controls the target risk at optimum.
 - Its solution $(\phi, \boldsymbol{p}_N^Y)$ is unique.



Results ○●○

t-SNE feature visualizations





(left) source, target and mapped source. (right) classes in source and target.

Performance on visual UDA datasets



Balanced accuracy (↑) over 10 runs with best performance in **bold**. Results are aggregated over imbalance scenarios and datasets.

Setting	Source	DANN	$WD_{\beta=0}$	$WD_{\beta=1}$	$WD_{\beta=2}$	MARSg	MARSc	IW-WD	OSTAR+IM	
Digits										
balanced	$\textbf{74.98} \pm \textbf{3.8}$	90.81 ± 1.3	92.63 ± 1.0	82.80 ± 4.7	76.07 ± 7.1	92.18 ± 2.2	94.91 ± 1.4	95.89 ± 0.5	$\textbf{97.51} \pm \textbf{0.3}$	
subsampled	75.05 ± 3.1	89.91 ± 1.5	89.45 ± 1.0	81.56 ± 4.8	77.77 ± 6.5	91.87 ± 2.0	93.75 ± 1.4	93.22 ± 1.1	$\textbf{96.69} \pm \textbf{0.7}$	
VisDA12										
original	$\textbf{48.63} \pm \textbf{1.0}$	53.72 ± 0.9	57.40 ± 1.1	47.56 ± 0.8	36.21 ± 1.8	55.62 ± 1.6	55.33 ± 0.8	51.88 ± 1.6	59.24 ± 0.5	
subsampled	42.46 ± 1.4	47.57 ± 0.9	47.32 ± 1.4	41.48 ± 1.6	31.83 ± 3.0	55.00 ± 1.9	51.86 ± 2.0	50.65 ± 1.5	$\textbf{58.84} \pm \textbf{1.0}$	
Office31										
subsampled	74.50 ± 0.5	76.13 ± 0.3	76.24 ± 0.3	74.23 ± 0.5	$\textbf{72.40} \pm \textbf{1.8}$	80.20 ± 0.4	80.00 ± 0.5	77.28 ± 0.4	$\textbf{82.61} \pm \textbf{0.4}$	
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Domain-invariant baselines designed for:

- Covariate shift w/o reweighting (DANN Ganin et al. 2016, WD_{β=0} Shen et al. 2018).
- GeTarS with reweighting $(WD_{\beta \in \{1,2\}} \text{ wu et al. 2019, MARS})$ Rakotomamonjy et al. 2021; IW-WD Combes et al. 2020.



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- OSTAR, a new general OT approach to align pretrained representations under Generalized Target Shift.
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Paper, code and contact

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Thank you for your attention !

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